

## PSD 40 - Shaft 5 mm solid

- Software features: spindle compensation drive, increased breakaway performance, synchronized run
- Software modules for IO-Link: changeover of parameter set, target speed in process data and modulo function
- Protection of internal electronics against manual operation
- Space-saving, compact design
- Galvanically separated supply voltages between control and motor and bus
- Precise position feedback thanks to an absolute measurement system without battery
- Optional gearbox for more torque
- Address may be set using the bus or an address switch (not for IO-Link)
- Status LEDs visible from the outside



Self-holding torque below at approx. 60 mA supply current and 0.5 A phase current, currentless 0 Nm.

Dimensions in mm.

See link Manual(s) for documentation and software.

**Type:** Horizontal

**Nominal Torque (Nm):** 0.8

**Nominal Speed (rpm):** 200

**Nominal Voltage (V DC):** 24 ( $\pm 10\%$ )

**Nominal Current (A):** 2.0

**Output Shaft (mm):** 5

**Output Shaft Type:** Solid

**Rotation Shaft / Housing:** Direct or  $0^\circ$

**BUS Communication:** Can Open (CA); IO-Link (IO); ProfiNet (PN); EtherCat (EC); Ethernet IP (EI)

**Electrical connection:** 0: Standard

**Protection Class:** IP50; IP65

**Motor:** Stepper motor

**Supply Voltage:** 24 V DC  $\pm 10\%$  galvanically separated between motor and control

**Measurement System:** Absolute without battery

**Accuracy:** " $\pm 0.7^\circ$  for versions with gearbox;  $\pm 1.8^\circ$  for versions without gearbox"

**Intermittence:** Start-up duration up to 50%

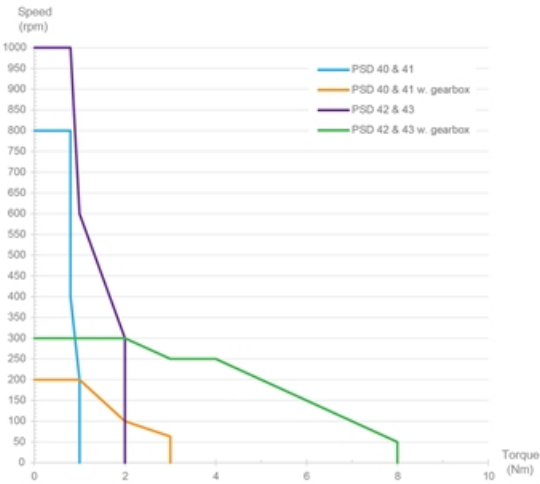
**Manual Adjustment:** No

**Brake:** No



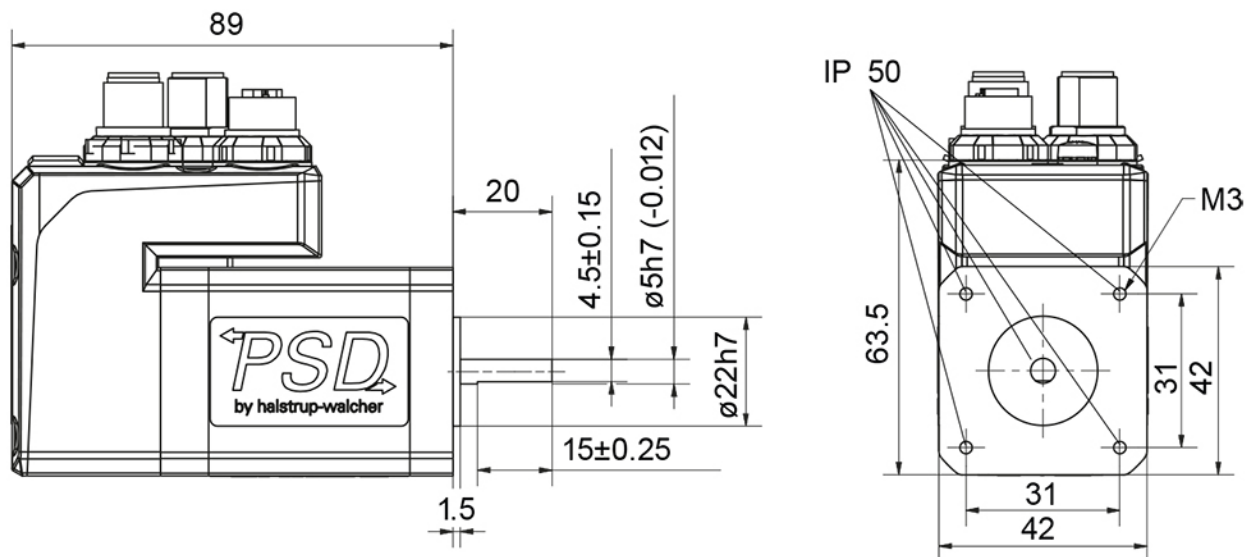
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Performance Curve - Direct Drives PSD



## General Data

### PSD 401-5V (solid shaft)



Designation	Nominal Torque (Nm)	Nominal Speed (rpm)	Nominal Current (A)	Self-holding Torque (Nm)	Max. Speed (rpm)
PSD 401-5V	0.8	200	2.0	0.4	800

Designation	Positioning Range (rot.)
PSD 401-5V	4026