

## PSD 40 - Shaft 14 mm hollow

- Software features: spindle compensation drive, increased breakaway performance, synchronized run
- Software modules for IO-Link: changeover of parameter set, target speed in process data and modulo function
- Protection of internal electronics against manual operation
- Space-saving, compact design
- Optional rotatable actuator housing
- Galvanically separated supply voltages between control and motor and bus
- Precise position feedback thanks to an absolute measurement system without battery
- Optional gearbox for more torque
- Address may be set using the bus or an address switch (not for IO-Link)
- Status LEDs visible from the outside



Self-holding torque below at approx. 60 mA supply current and 0.5 A phase current, currentless 0 Nm.

Dimensions in mm.

See link Manual(s) for documentation and software.

**Type:** Horizontal

**Nominal Voltage (V DC):** 24 (± 10 %)

**Nominal Current (A):** 2.0

**Output Shaft (mm):** 14

**Output Shaft Type:** Hollow

**Rotation Shaft / Housing:** Direct or 0°; 90°; 180°; 270°

**BUS Communication:** Can Open (CA); IO-Link (IO); ProfiNet (PN); EtherCat (EC); Ethernet IP (EI)

**Electrical connection:** 0: Standard

**Protection Class:** IP50; IP65

**Motor:** Stepper motor

**Supply Voltage:** 24 V DC ± 10 % galvanically separated between motor and control

**Measurement System:** Absolute without battery

**Accuracy:** "±0.7 ° for versions with gearbox; ± 1.8 ° for versions without gearbox"

**Intermittence:** Start-up duration up to 50%

**Manual Adjustment:** No

**Brake:** No

Performance Curve - Direct Drives PSD



## General Data

Designation	Nominal Torque (Nm)	Nominal Speed (rpm)	Nominal Current (A)	Self-holding Torque (Nm)	Max. Speed (rpm)
PSD 403-14H	3	50	2.0	1.5	200
PSD 401-14H	0.8	200	2.0	0.4	500

Designation	Positioning Range (rot.)
PSD 403-14H	986
PSD 401-14H	4026